

p -adic Representation Theory (PadicRep)

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Our goal is to formalize basics of p -adic representation theory.
Currently, we focus on \mathbb{C} -representations of p -adic groups.

Chapter 1

Td Groups

1.1 Definitions

Let G be a topological group. We say G is a *td group* (also called *l-group*), if G is totally disconnected, Hausdorff (T2), and locally compact.

Definition 1 (Van Dantzig's definition of td group). Let G be a topological group. We say that G has a *compact open subgroup basis* if $\mathcal{N}(1)$ has a basis consisting of compact open subgroups.

Now we want to prove Theorem 13, i.e. the two definitions of td group are equivalent.

Lemma 2. *Let G be a topological group. If G has a compact open subgroup basis, then G is a nonarchimedean group.*

Proof. □

Lemma 3. *Let G be a topological group. Then a neighborhood basis at unit 1 transports to a neighborhood basis at any $x \in G$ by left translation.*

Proof. □

Lemma 4. *A locally compact, Hausdorff, nonarchimedean group is totally disconnected.*

Proof. □

Lemma 5. *Let G be a td group. Then every neighborhood of 1 contains a compact clopen neighborhood of 1.*

Proof. □

Lemma 6. *Let G be a topological group. If K is compact and open subset of G , then there exists $V \in \mathcal{N}(1)$ such that $K \cdot V \subseteq K$.*

Proof. □

Lemma 7. *In Lemma 6, V can be chosen symmetric.*

Proof. □

Lemma 8.

Let G be a td group. Inside a compact clopen neighborhood of 1, there exists a compact open subgroup.

Proof. □

Lemma 9.

Let G be a td group. Every neighborhood of 1 contains a compact open subgroup of G .

Proof. □

Theorem 10 (Van Dantzig (forward direction)).

If G is td group (i.e. totally disconnected, locally compact, and Hausdorff topological group), then G has a compact open subgroup basis.

Proof. □

Lemma 11.

If a topological group G has a compact open subgroup basis, then G is locally compact.

Proof. □

Lemma 12.

If a topological group G has a compact open subgroup basis, then G is totally disconnected.

Proof. □

Theorem 13 (Van Dantzig).

Assuming G is Hausdorff, having a compact open subgroup basis is equivalent to being locally compact and totally disconnected.

Proof. □

Theorem 14.

Assuming G is Hausdorff, having a compact open subgroup basis is equivalent to being locally compact and nonarchimedean.

Proof. □

1.2 Example: $\mathrm{GL}_n(K)$ and Its Closed Subgroups

Let K be a non-archimedean local field. We use $M_n(K)$ to denote the ring of square matrices of size n with entries in K , and $\mathrm{GL}_n(K)$ to denote the general linear group.

Lemma 15. *The local field K is T2, locally compact, and totally disconnected.*

Proof. □

Lemma 16 (Topological Properties of Matrices). *For any $n \in \mathbb{N}$, the space $M_n(K)$ is totally disconnected, locally compact, and Hausdorff.*

Proof. This follows from the finite product topology of K , which possesses these properties. □

Lemma 17 (Topological Properties of $\mathrm{GL}_n(K)$). *For any $n \in \mathbb{N}$, the group $\mathrm{GL}_n(K)$ is a totally disconnected, locally compact, Hausdorff topological group.*

Proof. The group $\mathrm{GL}_n(K)$ is an open subset of $M_n(K)$ (as the preimage of K^\times under the continuous determinant map), so it inherits local compactness and total disconnectedness. It is Hausdorff as a subspace of a Hausdorff space. \square

Theorem 18. *The group $\mathrm{GL}_n(K)$ has a compact open subgroup basis.*

Proof. Since $\mathrm{GL}_n(K)$ is a td group (Lemma 17), the result follows directly from the forward direction of Van Dantzig's theorem (Theorem 10). \square

Lemma 19. *Let G be a td group (totally disconnected, locally compact, Hausdorff). Any closed subgroup of G is also a td group.*

Proof. Closed subgroups of locally compact groups are locally compact. Subspaces of totally disconnected Hausdorff spaces are totally disconnected and Hausdorff. \square

Chapter 2

Continuous Representations of Groups with Topology

2.1 Continuous representations

Let R be a commutative topological ring, G a group equipped with a topology, and V a topological R -module with continuous addition and scalar multiplication.

Definition 20 (Continuous representations). A *continuous representation* is a representation $\rho : G \rightarrow \text{Aut}_R(V)$ whose action map $(g, v) \mapsto \rho(g)v$ is continuous. (In Lean this is defined as a subtype of `Representation` equipped with the continuity proof.)

Definition 21 (Constructor). Given a representation ρ and a proof of continuity of the action map, we obtain a continuous representation.

Lemma 22 (Projections and coercions). (*In dependent type theory/kean*) All definitional projections and coercions agree with the data used to build the representation.

Proof. □

Definition 23 (Action map). We have the action map $G \times V \rightarrow V$ associated to a continuous representation.

Lemma 24 (Continuity of the action). *The action map of a continuous representation is continuous by construction.*

Proof. □

Definition 25 (Underlying topological module). The underlying topological R -module is bundled as an object of `TopModuleCat(R)`.

Definition 26 (From `TopModuleCat`). If M is an object of `TopModuleCat(R)` equipped with a continuous action by R -linear maps, this yields a continuous representation.

Lemma 27 (Slice continuity). *For a continuous representation ρ :*

1. *for fixed g , the map $v \mapsto \rho(g)v$ is continuous;*
2. *for fixed v , the map $g \mapsto \rho(g)v$ is continuous;*

3. for fixed g and u , the affine map $v \mapsto \rho(g)v + u$ is continuous.

Proof.

□

Lemma 28 (Extensionality). *Two continuous representations are identical exactly when their underlying algebraic representations are identical.*

Proof.

□

Lemma 29 (Trivial representations). *The trivial representation is a continuous representation.*

Proof.

□

Definition 30 (Restriction). A continuous representation restricts to any subgroup $H \leq G$.

Definition 31 (Descent to a quotient). Assuming G has continuous multiplication, if $N \trianglelefteq G$ and ρ is trivial on N , then ρ descends to a continuous representation of G/N .

2.2 The category of continuous representations

Definition 32 (The category $\text{CRep}_R(G)$). The category $\text{CRep}_R(G)$ is the category of continuous actions of G on topological R -modules, implemented as a category of continuous G -actions in $\text{TopModuleCat}(R)$.

We defined $\text{CRep}_R(G)$ using a more abstract way, i.e. group actions on the category $\text{TopModuleCat}(R)$ for Lean implementation considerations.

Therefore, we need to show that this abstract definition coincide with the natural one, i.e. the category of continuous representations of G .

Definition 33 (Underlying topological module). There is a forgetful functor to $\text{TopModuleCat}(R)$ and an induced map on morphisms.

Definition 34 (Action data). For $V \in \text{CRep}_R(G)$ we extract the underlying action and define the evaluation map $\text{act}(g, v)$.

Lemma 35 (Action continuity). *The action map $G \times V \rightarrow V$ is jointly continuous.*

Proof.

□

Definition 36 (Forget to algebraic representations). There is a forgetful functor $\text{CRep}_R(G) \rightarrow \text{Rep}_R(G)$.

Definition 37 (Associated continuous representation). Every object in $\text{CRep}_R(G)$ yields a continuous representation on its underlying type.

Proof.

□

Lemma 38 (Pointwise continuity). *Joint continuity of the action implies continuity of each slice $v \mapsto \rho(g)v$.*

Proof.

□

Definition 39 (Action endomorphisms). Each group element acts by a continuous endomorphism of the underlying topological module, and these assemble into a monoid homomorphism $G \rightarrow \text{End}(V)$.

Definition 40 (Action object from a representation). A representation with a jointly continuous action determines a continuous action object in $\text{TopModuleCat}(R)$.

Definition 41 (Upgrade a representation). A representation with a compatible topology and continuous action determines an object of $\text{CRep}_R(G)$.

Definition 42 (From a continuous representation). A continuous representation (as defined above) can be lifted to an object of $\text{CRep}_R(G)$.

Chapter 3

The Hecke Algebra of a Td Group

3.1 Locally constant functions and distributions on a td space

Let X be a td space (i.e. totally disconnected, locally compact, Hausdorff space).

Definition 43 (Locally constant functions). We write $C^\infty(X)$ for the space of complex-valued locally constant functions on X .

Definition 44 (Compactly supported locally constant functions). We write $C_c^\infty(X)$ for locally constant functions with compact support.

Definition 45 (Distributions). A *distribution* on X is a \mathbb{C} -linear functional on $C_c^\infty(X)$.

Lemma 46 (Linearity). *Distributions are additive and \mathbb{C} -linear.*

Proof. □

3.1.1 Extension by zero and restriction

Definition 47 (Extension by zero). Given a locally constant function on a subset $Z \subseteq X$, we extend it to X by zero outside Z .

Lemma 48 (Local constancy of the extension). *If Z is clopen, the extension by zero is locally constant.*

Proof. □

Lemma 49 (Compact support of the extension). *If Z is closed and compact, the extension by zero has compact support.*

Proof. □

Definition 50 (Restriction of a distribution). A distribution on X restricts to a subspace Z by evaluating on the extension by zero of test functions on Z .

Definition 51 (Support of a distribution). The support of a distribution F consists of those points x such that every neighborhood of x contains a test function on which F does not vanish.

Lemma 52 (Support is closed). *The support of a distribution is a closed subspace of X .*

Proof. □

Lemma 53 (Vanishing on disjoint support). *If the support of a test function is disjoint from the support of F , then F evaluates to zero on that function.*

Proof. □

3.2 Distributions on groups

Let G be a totally disconnected, locally compact, Hausdorff topological group.

3.2.1 Translations of functions

Definition 54 (Translations). For $\varphi : G \rightarrow \mathbb{C}$ and $g \in G$ we define

$$(R_g\varphi)(x) = \varphi(xg), \quad (L_g\varphi)(x) = \varphi(g^{-1}x).$$

Lemma 55 (Translation preserves structure). *Right and left translations preserve local constancy and compact support.*

Proof. □

Definition 56 (Translation on $C_c^\infty(G)$). Translations of test functions are defined and satisfy the expected identities.

3.2.2 Compactly supported distributions and convolution

Definition 57 (Compactly supported distributions). A compactly supported distribution is a distribution whose support is compact.

Definition 58 (Convolution test function). Given D and φ , the function $x \mapsto D(R_x\varphi)$ is locally constant and compactly supported, and hence defines an element of $C_c^\infty(G)$.

Definition 59 (Convolution). The convolution of F and D is defined by

$$(F * D)(\varphi) = F(x \mapsto D(R_x\varphi)).$$

Lemma 60 (Associativity). *Convolution of compactly supported distributions is associative.*

Proof. □

3.2.3 Translation actions on distributions

Definition 61 (Actions on distributions). Left and right translation actions are defined by dualizing the actions on test functions.

3.2.4 Delta distributions and a normalized Haar distribution

Definition 62 (Delta distributions). The delta distribution at g evaluates test functions at g .

Definition 63 (Indicator functions). The indicator function of a compact clopen subset is a compactly supported locally constant function.

Definition 64 (A normalized Haar distribution). We define a compactly supported distribution e_H attached to a compact open subgroup H as the average of a test function over H with respect to the normalized Haar measure on H .

3.2.5 Convolution identities for delta and normalized Haar distributions

Lemma 65 (Idempotence of the normalized Haar distribution). *For a compact open subgroup H , the normalized Haar distribution is idempotent:*

$$e_H * e_H = e_H.$$

Proof. □

Lemma 66 (Convolution with delta distributions). *For $g \in G$ and test function φ :*

$$(\delta_g * e_H)(\varphi) = e_H(R_g\varphi), \quad (e_H * \delta_g)(\varphi) = e_H(L_{g^{-1}}\varphi).$$

*If $g \in H$, then $\delta_g * e_H = e_H * \delta_g$.*

Proof. □

3.2.6 Invariance of the normalized Haar distribution

Lemma 67 (Left/right/bi-invariance of the normalized Haar distribution). *For a compact open subgroup H , e_H is left H -invariant, right H -invariant, and hence bi- H -invariant.*

Proof. □

3.2.7 Finite decomposition for bi-invariant distributions

Theorem 68 (Decomposition into convolutions with delta distributions). *If F is compactly supported and bi- H -invariant, then there exist finitely many elements $g_i \in G$ and coefficients $a_i \in \mathbb{C}$ such that*

$$F(\varphi) = \sum_i a_i ((e_H * \delta_{g_i})(\varphi))$$

for all test functions φ .

Proof. □

3.2.8 Local constancy (smoothness)

Definition 69 (Invariant distributions). We say a distribution is left, right, or bi-invariant under an open subgroup if it is fixed by the corresponding translation action.

Theorem 70 (Locally constant distributions). *Let D be a compactly supported distribution on G . The following statements are equivalent:*

1. D is left-invariant under some compact open subgroup of G ;
2. D is right-invariant under some compact open subgroup of G ;
3. D is bi-invariant under some compact open group of G .

A compactly supported distribution satisfying the above condition is said to be locally constant.

Proof. □

3.3 The Hecke algebra

Definition 71 (Hecke algebra). The Hecke algebra $\mathcal{H}(G)$ is the space of compactly supported, locally constant distributions on G , equipped with convolution.

Lemma 72 (Basic structure maps). *(In dependent type theory/lean) The Hecke algebra is a subtype of compactly supported distributions with the expected coercions and extensionality.*

Proof. □

Lemma 73 (Additive and scalar structure). *Addition, negation, and scalar multiplication agree with the underlying distribution operations.*

Proof. □

Lemma 74 (Convolution product). *Convolution makes $\mathcal{H}(G)$ into a non-unital ring; associativity is inherited from convolution of distributions.*

Proof. □

3.4 TODOs

Definition 75. Define idempotent algebra.

Definition 76. Define non-degenerated (also called unital) modules over an idempotent algebra.

Theorem 77. *Hecke algebra is an idempotent algebra.*

Proof. □

Definition 78. Define the category of non-degenerated modules over the Hecke algebra.

Theorem 79 (Main theorem). *The category of non-degenerated modules over the Hecke algebra of G is equivalent to the category of smooth \mathbb{C} -representations of G .*

Proof. □